Boston Gear®

Ratiotrol®

DC Motor Speed Control

P-3035-BG

Installation and Operation

Doc. No. 83531

RP1, RP1R 1/6-1/2 HP RP2, RP2R 3/4-1 HP





GENERAL INFORMATION

Description

Boston Gear Ratiopax Controllers statically convert single-phase AC line power to regulated DC for adjustable-speed armature control of shunt wound and permanent magnet motors.

Model Types

Table 1. Model Types

	Function				Power	Power Output	
Model	Regulated Power Conversion	Uni-directional Run-Stop	Reversing Run-Stop	HP Range	Source (single Phase)	Armature	Field
RP1	Х	Х		1/6 - 1/2	115V	0 - 90	50
RP1R	Х		Χ		50 or 60 Hz		
RP2	Х	Х		3/4 - 1	230V	0 - 180	100
RP2R	Х		Χ		50 or 60 Hz	0 - 100	100

Enclosure

Nonventilated, dust resistant, NEMA Type 1, constructed of die-cast aluminum alloy.

Ratings

1.	Service Factor	1.0
2.	Duty	Continuous
3.	Overload Capacity	150% for 1 minute
	AC Line Fuse Interrupting Capacity	
	Speed Control Pot	•

Table 2. Ratings

	Ratings							
R	1/6	1/4	1/3	1/2	3/4	1		
	Rated Kilowatts	(KW)	0.124	0.187	0.249	0.373	0.560	0.746
1 Dhoop AC Input	Line	115 VAC Controller	3.9	5.0	6.0	8.7		
1-Phase AC Input (Full Load)	Amps	230 VAC Controller					5.9	8.8
(Full Loau)	KVA		.48	.58	.71	1.0	1.4	2.0
DC	Motor Armature Amps Motor (1) Field	90 VDC	2.0	2.8	3.5	5.4		
Output		180 VDC					3.8	5.5
(Full Load)		50 VDC	1.0	1.0	1.0	1.0		
(Full Load)	Amps	100 VDC					1.0	1.0
Full-Load Torque (lb. ft.) with 1750 RPM Base Speed Motor			0.5	0.75	1.0	1.5	2.2	3.0
Minimum Transformer KVA for Voltage Matching or Isolation			0.5	0.75	0.75	1.0	1.5	2.0
Controller	Approximate Weight		2.0 lbs. (0.9kg.)					
Physical Data	Standard Dimensions		See Figure 2					

⁽¹⁾ Not applicable with permanent magnet motors.

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Operator Controls

The operator controls, integrally mounted on the front panel, include the following:

Models RP1 and RP2 - A calibrated SPEED control pot and a RUN/STOP toggle switch.

Model RP1R and RP2R - A calibrated SPEED control pot and a FORWARD/STOP/REVERSE toggle switch. The reversing switch has a center position detent which provides antiplug protection.

Operating Conditions

1.	Line voltage Variation	+/-10% of rated
2.	Line Frequency Variation	+/-2 Hertz
3.	Ambient Temperature range	0 to 40°C (32°F to 104°F)
4.	Altitude (standard)	1000 meters (3300 feet) maximum

Table 3. Speed Regulation Characteristics

Regulation Method	Variables				
Voltage Feedback with IR	Load change 95%	Line Voltage +/-10%	Field Heating Cold/Normal	Temperature +/- 10%	Speed Range
Compensation	2%	+/-1%	5-12%	+/-2%	20:1

Performance Characteristics

1. Controlled Speed Range 0 to motor base speed

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Installation and Wiring

- Report shipping damage to the carrier.
- 2. Unpack the controller and remove all packing material.
- 3. Remove the four screws on the front cover, and remove the cover from the enclosure.
- 4. Check components in the controller. All damaged components must be replaced.
- 5. The controller can be surface mounted, or the front cover can be removed and panel mounted. Never mount the controller immediately beside or above heat-generating equipment, or directly below water or steam pipes. If the controller is mounted in an enclosure, be sure the temperature in the enclosure does not exceed 55°C (131°F).

Note: Never mount the operator controls remotely.

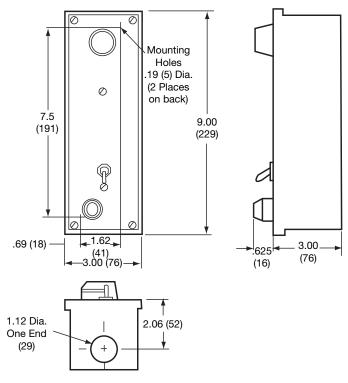
- 6. If the controller is subjected to vibrations, it must be shock mounted.
- 7. Be sure the line voltage and frequency are compatible with the controller rating.
 - a. SEPARATE OVERCURRENT PROTECTION IS REQUIRED BY THE NATIONAL ELECTRICAL CODE. THE USER IS RESPONSIBLE FOR CONFORMING WITH THE NATIONAL ELECTRICAL CODE AND ALL APPLICABLE LOCAL CODES WHICH GOVERN SUCH PRACTICES AS WIRING PROTECTION, GROUNDING, DISCONNECTS, AND OTHER PROTECTION.
 - b. THE AVAILABLE SHORT-CIRCUIT CURRENT OF THE INPUT SUPPLY MUST BE LESS THAN 5,000 AMPERES SYMMETRICAL OR CONTROLLER DAMAGE MAY OCCUR.

Short-circuit current can be limited by sizing the input supply transformer at 50 KVA or less, or by using correctly sized current limiting fuses in the input supply to the controller. Do not size the transformer less than the minimum transformer KVA listed in Table 2.

c. NEVER USE POWER FACTOR CORRECTION CAPACITORS ON THE INPUT LINE TO THE CONTROLLER. These capacitors can damage the solid-state components.

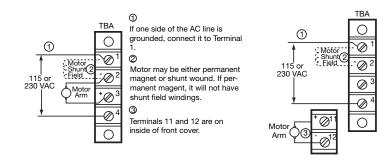
- Use T & B 8225 fitting (or equal) to attach 3/4" conduit to the controller.
- Use #14 AWG stranded wire for controller connections. Oversized or solid wire can break terminal strip barriers.

Figure 2. Ratiopax Dimensions



- 10. Connect the motor and single-phase power to the controller as shown in Figure 3.
- 11. Connect earth ground to the ground connection post inside the controller enclosure or to a front cover screw.

Figure 3. Connections



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Startup and Operation

 Recheck the wiring to the controller before applying power.

IF ONE OF THE AC SUPPLY LINES IS GROUNDED, IT MUST BE CONNECTED TO TERMINAL 1.

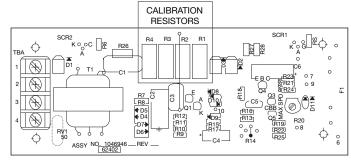
- 2. Remove the correct calibration resistor(s) from the controller circuit board with a wire cutter, as shown in Table 4 and Figure 4.
- 3. Replace the front cover on the enclosure and tighten the four screws.

Controlle	Remove		
Models RP1, RP1R	Models RP2, RP2R	Resistors	
1/6		R2, R3, R4	
1/4		R3, R4	
1/3	3/4	R4	
1/2	1	None	

Table 4. Calibration Wires

- 4. Turn the SPEED control pot to zero on its dial.
- 5. Place the RUN/STOP/FORWARD/STOP/ REVERSE switch (whichever is applicable) in STOP position.
- 6. Apply AC input power to controller.

Figure 4. Circuit Board



Note: Varistor RV1 is located on 230V circuit boards only.

- 7. Place the RUN/STOP switch in Run position or place the FORWARD/STOP/REVERSE switch in FORWARD position (whichever is applicable).
- 8. Turn the SPEED control pot slowly until the motor rotates.
- 9. If motor rotation is opposite to that desired, place the switch in STOP position, turn-off the AC input power, and interchange the motor armature leads at the motor connection box.

NEVER USE LINE SWITCHING TO START AND STOP THE MOTOR. Resulting transients can damage the controller.

- Models RP1R and RP2R only: To obtain opposite motor rotation, place the FORWARD/STOP/ REVERSE switch in STOP position and then in REVERSE position.
- 11. To obtain top speed, turn the SPEED control pot to 100 on its dial.

Maintenance

Maintenance consists of keeping the controller clean and dry. Refer to maintenance instructions supplied by the motor manufacturer. If the motor doesn't rotate, check the fuse on the controller front cover. If the fuse is blown, replace it with an exact replacement.

SUBSTITUTE FUSES CAN CAUSE CONTROLLER DAMAGE.

If the replacement fuse blows, turn-off the AC input power and refer to Table 5. Most controller failures are caused by incorrect connections, overload, or the accumulation of dirt, dust, or moisture. If motor operation becomes faulty, proceed as follows:

BE SURE THE AC INPUT POWER IS TURNED-OFF BEFORE WORKING ON THE CONTROLLER. HIGH VOLTAGE IN THE CONTROLLER CAN CAUSE ELECTRIC SHOCK RESULTING IN PERSONAL INJURY OR LOSS OF LIFE.

- 1. Check for:
 - a. Blown fuse
 - b. Loose or missing terminal screws
 - c. Unattached wires
 - d. Charred, darkened, or punctured components and wires
- 2. If the SPEED control pot feels rough or stiff when rotated, an open or shorted pot is indicated.
- 3. Measure the AC input voltage to the controller on Terminals 1 and 4, and compare with controller rating.

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Table 5. Troubleshooting

Inc	lication	Possible Cause	Corrective Action
1.	Controller fuse	Wiring faulty, incorrect or	Check all external wiring
	blows when AC	grounded.	terminating in the controller.
	input power is	Motor shunt field shorted	Repair or replace motor.
	applied to the	or grounded.	
	controller.	Components shorted.	Repair or replace controller.
2.	Controller fuse	Motor armature shorted or	Repair or replace motor.
	blows when RUN/	grounded.	
	STOP switch is	Shorted SCR SCR1 or	Replace circuit board or SCR.
	placed in RUN	SCR2, or circuit board.	
	position.		
3.	Controller fuse	Loose or corroded	Check all terminal connections
	blows while motor	connection, or wiring	and wiring between the line,
	is running.	faulty, incorrect or	controller, and motor.
		grounded.	Check motor armature current.
			If current exceeds controller
			rating, check for a mechanical
			overload or faulty motor. Also
			check shunt field current. Low
			shunt field current causes
			excessive armature current.
		Circuit board failure.	Replace circuit board.
4.	Motor does not	Wiring faulty, incorrect, or	Check all external wiring
	rotate.	grounded.	terminating in the controller.
		Controller fuse blow.	Replace fuse with exact
			replacement.
		SPEED control pot failure	Replace pot.
		RUN/STOP OR FORWARD/	Replace switch.
		STOP/REVERSE switch	
		failure.	
		Controller failure.	Repair or replace controller.
5.	Motor does not	Low line voltage.	Check for rated line voltage
	reach base speed.	•	+/- 10%.
		Motor overloaded.	See Indication 3.
		MAX SPD pot R20	Turn R20 clockwise until top
		misadjusted.	speed is reached.
		Circuit board failure.	Replace circuit board.
6.	Unstable speed,	Wrong calibration resistor(s)	See Tables 4 and 5.
	inadequate regulation,	removed.	
	or low torque.	Motor faulty.	Check motor commutator and
	-	-	brushes. Refer to motor
			manufacturer's instructions.
		Circuit board failure.	Replace circuit board.

Table 6. Parts List

Part	Part Number		Part	Part Number		
rait	Models RP1, RP1R	Models RP2, RP2R	Fait	Models RP1, RP1R	Models RP2, RP2R	
Circuit Board	60152	60155	SCR, SCR1, SCR2	67492	67492	
Fuse, F1, 10A 250V	60652	60652	Switch FWD/ST0P/REV	63379	63379	
Fuse Holder	63804	63804	Switch RUN/STOP	63374	63374	
Pot, Speed	63376	63376	Transformer T	60868	60869	

Warranty

Boston Gear warrants that products manufactured or sold by it shall be free from defects in material and workmanship. Any products which shall within two (2) years of delivery, be proved to the Company's satisfaction to have been defective at the time of delivery in these respects will be replaced or repaired by the Company at its option. Freight is the responsibility of the customer. The Company's liability under this limited warranty is limited to such replacement or repair and it shall not be held liable in any form of action for direct or consequential damages to property or person. The foregoing limited warranty is expressly made in lieu of all other warranties whatsoever, express, implied and statutory and including without limitation the implied warranties of merchantability and fitness.

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