# **Modular Control Components**

### **BXCTRL**

Tension Control (P/N 6910-448-306)



## **Tension Controller**

The BXCTRL controller is a solid state electronic control that receives signal from a Dancer pivot point sensor or 2 Load cells. It integrates 2 separate Digital PID Controllers and 2 separate Open Loop controls.

All setup can be made through a user friendly application and saved to the integrated memory, an SD card or your computer. Wire up to two Load cells or a Dancer arm to get a closed loop control with a linear or auto. compensation.

When associated with the BX2DRV, the controller becomes the BXCTRL-BX2DRV. Power supply, input and communication will be made by an internal connection.

#### **Specifications**

| Main Supply Voltage           | 24VDC +/-5%   |
|-------------------------------|---|
| 2 Channels Sensors Input      | Dancer Arm or up to<br>two Load Cells<br>(customer provided)  |
| 2 Channels Output             | Selectable 0-10V or<br>4-20mA through<br>an application   |
| 2 PID Controller              | PID Gain adjustable with the application  |
| USB Connection                | Connect your BXCTRL to<br>your computer with a<br>USB cable and get access<br>to the application        |
| User Friendly Application     | Setup all parameters<br>through a user friendly<br>application and get a<br>graphic overview.           |
| Parameters Partitions Saving  | Through the application<br>save your parameter<br>partitions on your<br>computer or in an SD card.      |
| Open Loop Control             | Get an open loop<br>control by wiring an<br>external sensor. Selectable<br>0-10V or 4-20mA              |
| Linear and Auto. Compensation | Get a closed loop control<br>with a linear or auto.<br>compensation. Selectable<br>with the application |

# **Modular Control Components**

#### **BX2DRV**

Driver (P/N 6910-448-305)



#### **BXCTRL-BX2DRV**

Driver (P/N 6910-448-307)



### **Tension Controller**

This double channel driver can accept both voltage (0-10V) or current loop (4-20mA) input signals.

With being associated to a remote potentiometer, it will become an Open Loop Control, permitting then to manually control the braking torque.

Optional Rail DIN fixation available.

For use with TB, ATT and MPB or MPC unit. POB, PRB-H, PTB, PMC, PHC or POC. Sizes 10 or smaller.

#### **Specifications**

| Main Supply Voltage                              | 24V DC +/-5%   |
|--|--|
| 2 Channels 4A Output<br>2 Analog Input           | 0-24V or 0-4A<br>Selectable with Anti<br>residual<br>0-10V or 4-20mA |
|  | Selectable   |
| Easy to set up                                   | ON and OFF Mode<br>Inputs  |
| 2 Auxiliary Inputs with a<br>Calibration Feature | Get an open loop<br>control with a roll<br>diameter compensation     |
|  | Sensor Input 0-10V or<br>4-20mA Selectable                           |

## **Tension Control/Driver**

Combines control and driver characteristics of BXCTRL and BX2DRV with a 24 volt driver in a single housing.

## **Modular Control Components**

### **XPRO**

Tension Control System (P/N 6910-448-308)

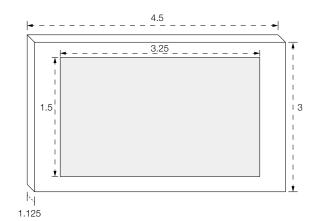


### **Tension Control System**

The XPRO human interface is an optional component to the Warner Electric BXCTRL control which is providing to the user an easy way to get access to the PID regulation SetPoint.

It is generally used with load cells application when the current Tension needs to be changed when running.

It's offering some display screens which could be setup to show some curves or some other data as the current tension, the real time output voltage.



## **Modular Control Components**

#### **Electro-Pneumatic Transducer**

(P/N 6910-101-066)



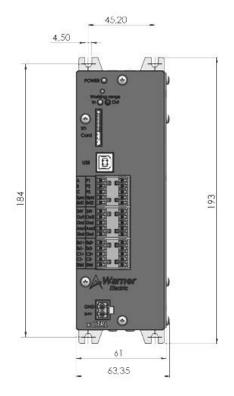
Used for interfacing with pneumatic brakes. Warner Electric offers a convenient package that consists of an air filter with automatic moisture drain, together with one I/P (current-pressure) transducer.

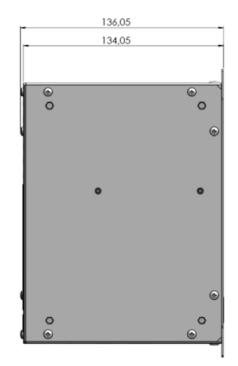
#### **Specifications**

| Input signal               | 4–20mA   |
|----------------------------|--|
| Output range               | 0–120 Psig.  |
| Supply pressure            | 20–150 Psig.<br><b>Note:</b> Supply pressure to the<br>transducer must always be at<br>least 5 Psig. above the maximum<br>output pressure required for the<br>brake. |
| Temperature range          | -20°F to 150°F   |
| Minimum air<br>consumption | 6.0 (SCFH) at 15 Psig.   |
| Supply pressure effect     | 1.5 Psig. for 25 Psig. supply change   |
| Pipe size                  | 1/4" NPT (transducer and filter)   |

# **Modular Control Components**

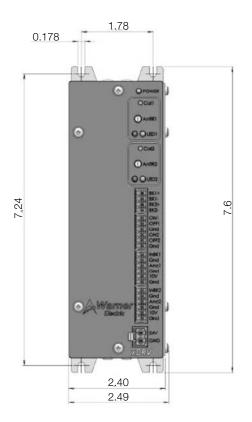
### **BXCTRL Dimensions**

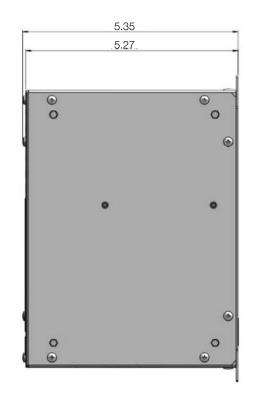




# **Modular Control Components**

## **BX2DRV** Dimensions





## **Analog/Manual Control for Electric Brake Systems**

## TCS-200-1

(P/N 6910-448-086)

#### TCS-200-1H (P/N 6910-448-087)

#### TCS-200 (P/N 6910-448-126)

**TCS-200-1-C** (P/N 6910-448-089) (not shown)



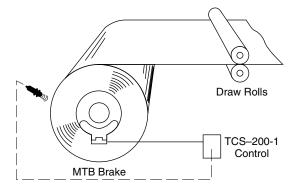
### **Analog/Manual Control**

The Analog/Manual Control is a basic, low cost, open loop control for manual type operation of Electro Disc tension brakes. A remote torque control function is available that enables the operator to control the desired tension from any convenient location. A roll follower feature provides automatic adjustment of brake torque proportional to roll diameter change. For the TCS-200-1 and TCS-200-1H analog inputs can be followed.

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WARNER ELECTRIC TCS-200-1

## **Typical System Configuration**



The complete system consists of:

- 1. Tension brake
- 2. Analog tension control
- 3. Control power supply
- 4. Optional sensor inputs (customer supplied)

The control unit maintains a current output to the tension brake based on an analog input or the manual setting of the control tension adjustment dials. Varying the current from the control creates more or less brake torque for tension adjustability.

### **Specifications**

| Input<br>TCS-200<br>TCS-200-1, TCS-200-1H                 | 24–30 VAC, ±10%, 56/60 Hz, single phase<br>115/230 VAC, ±10%, 50/60 Hz, single phase  |
|---|---|
| Output<br>TCS-200   | PWM full wave rectified, 0-3.24 amps  |
| TCS-200-1   | current controlled<br>Adjustable 0–24 VDC, 4.25 amps  |
| TCS-200-1H  | maximum continuous<br>Adjustable 0–24 VDC<br>Maximum of 5.8 amps continuous   |
|   | Can be used with any 24 VDC tension brake.<br>TCS-200 requires sense coil for operation.<br>Sense Coil – 275-3893<br>TCS-200-1 and TCS-200-1H can be used             |
| • • • • <b>-</b> •  | with or without sense coil.   |
| Ambient Temperature<br>TCS-200<br>TCS-200-1, TCS-200-1H   | -20° to +115°F (-29° to +46°C)<br>-20° to +125°F (-29° to +51°C)  |
| Sensor Inputs   |   |
| Remote Torque Adjust<br>TCS-200, TCS-200-1,<br>TCS-200-1H | 1000 ohms   |
| Roll Follower   |   |
| TCS-200<br>TCS-200-1, TCS-200-1H                          | 10K ohms<br>1000 ohms   |
| Analog Voltage Input                                      |   |
| TCS-200-1, TCS-200-1H                                     | 0–10 VDC (optically isolated when used with an external 15–35 VDC supply)   |
| Analog Current Input<br>TCS-200-1, TCS-200-1H             | 4–20 mA (optically isolated when used with an external 15–35 VDC supply)  |
| Auxiliary Inputs  |   |
| Brake Off (all models)                                    | Removes output current to the brakes. Puts the brake at zero current.   |
| Brake On (all models)                                     | Applies full voltage to the connected brake.  |
| Front Panel Adjust  |   |
| Tension Adjust<br>(all models)                            | Provides current adjust to the brake from   |
|   | 0–100%.   |
|   | In the remote mode, provides for maximum output level set to the brake.   |
| Brake Mode Switch   |   |
| (all models)  | Allows for full brake on, run, or brake off modes of operation to the brake.  |
| Indicators (all models)                                   | Green LED power indicator showing AC power is applied to the control.   |
|   | Red LED short circuit indicator showing<br>shorted output condition. Resettable by going<br>to brake off mode with front panel switch.                                |
| General (all models)                                      | The control chassis must be considered NEMA<br>1 and should be kept clear of areas where<br>foreign material, dust, grease, or oil might<br>affect control operation. |
| Note: When used with othe                                 | er than MTB magnets, inductive load must be   |

**Note:** When used with other than MTB magnets, inductive load must be supplied – PN 275-3843. Consult factory for details.